

Read this document carefully before using this device. The guarantee will be expired by device demages if you don't attend to the directions in the user manual. Also we don't accept any compensations for personal injury, material damage or capital

ENDA ET SERIES PID TEMPERATURE CONTROLLER

Thank you for choosing ENDA ET SERIES PID temperature controller.

- Selectable dual setpoint.
- Selectable thermocouple types.
- Automatic calculation of PID parameters (SELFTUNE).

Selftune for automatic PID calculation or

nanually enter PID parameters if known.

- Three different specifications can be assigned to digital input.
- Three different specifications can be assigned to F function key. Þ
- Soft-Start feature
- Selectable SSR control output.
- C/A2 Relay output programmable as secondary alarm or control output.
- A1 Relay output programmable as primary alarm or PID cooling output.

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- Selectable heating/cooling control.
- Zero point input shift.

4420....48x48x87mm 7420....72x72x97mm 8420....48x96x87mm 9420....96x96x50mm

1 - Size

- In case of sensor failure, manually, periodical or auto-periodical control can be selected.
- RS485 ModBus protocol communication feature (optional).

2 - Supply Voltage UV.....90-250V AC

LV.....10-30V DC

8-24V AC

CE marked according to European Norms.

Order Code : ET 4 2 0 -2

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Input Type	Temperature Range		Accuracy			
		°C	°F			
PT100 Resistance thermometer	EN 60751	-199.9600.0 °C	-199.9999.9 °F	± 0,2% (of full scale) ± 1 digit		
PT100 Resistance thermometer	EN 60751	-200600 °C	-3281112 °F	\pm 0,2% (of full scale) \pm 1 digit		
J (Fe-CuNi) Thermocouple	EN 60584	-30.0600.0°C	-22.0999.9 °F	\pm 0,5% (of full scale) \pm 1 digit		
J (Fe-CuNi) Thermocouple	EN 60584	-30600°C	-221112 °F	$\pm 0,5\%$ (of full scale) ± 1 digit		
K (NiCr-Ni) Thermocouple	EN 60584	-30.0999.9°C	-22.0999.9 °F	\pm 0,5% (of full scale) \pm 1 digit		
K (NiCr-Ni) Thermocouple	EN 60584	-301300°C	-222372 °F	$\pm 0,5\%$ (of full scale) ± 1 digit		
L (Fe-CuNi) Thermocouple	DIN 43710	-30.0600.0°C	-22.0999.9 °F	\pm 0,5% (of full scale) \pm 1 digit		
L (Fe-CuNi) Thermocouple	DIN 43710	-30600°C	-221112 °F	$\pm 0,5\%$ (of full scale) ± 1 digit		
T (Cu-CuNi) Thermocouple	EN 60584	-30.0400.0°C	-22.0752.0 °F	\pm 0,5% (of full scale) \pm 1 digit		
T (Cu-CuNi) Thermocouple	EN 60584	-30400°C	-22752 °F	$\pm 0,5\%$ (of full scale) ± 1 digit		
S (Pt10Rh-Pt) Thermocouple	EN 60584	-401700°C	-403092 °F	\pm 0,5% (of full scale) \pm 1 digit		
R (Pt13Rh-Pt) Thermocouple	EN 60584	-401700°C	-403092 °F	\pm 0,5% (of full scale) \pm 1 digit		
B (Pt30Rh-Pt6Rh) Thermocouple	EN 60584	2001700°C	3923092 °F	$\pm 0,5\%$ (of full scale) ± 1 digit		
ENVIRONMENTAL CONDITI	ONS					
Ambient/storage temperature	Ambient/storage temperature 0 +50°C/-25 +70°C (with no icing)					
Max. Relative humidity	Max. Relative humidity Relative humidity 80% for temperatures up to 31°C decreasing linearly to 50% relative humidity at 40°C.					
Rated pollution degree	Rated pollution degree According to EN 60529 Front panel : IP65, Rear panel : IP20					
Height	Height Max. 2000m					

Do not use the device in locations subject to corrosive and flammable gases.

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ELECTRICAL CHARACTERISTICS						
Supply	90-250V AC 50/60Hz, 10-30V DC / 8-24V AC SMPS					
Power consumption	Max. 5VA					
Wiring	Power connector: 2.5mm ² screw-terminal, Signal connector: 1,5mm ² screw-terminal conenction.					
Line resistance	Max. 100ohm					
Data retention	EEPROM (minimum 10 years)					
EMC	EN 61326-1: 2013					
Safety requirements	EN 61010-1: 2010 (Pollution degree 2, overvoltage category II)					
OUTPUTS						
C/A2 output	Relay : 250V AC, 8A (for resistive load), Selectable as NO+NC Control or Alarm2 output.					
A1 output	Relay : 250V AC, 8A (for resistive load), NO (Selectable as Alarm1 and Cooling Control output).					
SSR output	Max 20mA 24Volt					
Life expectancy for relay	Mechanical 30.000.000; Electrical 100.000 operation. 250V AC, 8A (resistive load).					
CONTROL						
Control type	Single set-point and alarm control					
Control algorithm	On-Off / P, PI, PD, PID (selectable)					
A/D converter	12 bit					
Sampling time	100ms					
Proportional band	Adjustable between 0% and 100%. If Pb=0.0%, On-Off control is selected.					
Control period	Adjustable between 1 and 125 seconds					
Hysteresis	Adjustable between 1 and 50°C/F					
Output power	The ratio of power at a set point can be adjusted between 0% and 100%					
HOUSING						
Housing type	Suitable for flush-panel mounting according to DIN 43 700.					
Dimensions	ET4420 : G48XY48XD87MM ET7420 : G72XY72XD97MM ET8420 : G48XY96XD87MM ET9420 : G96XY96XD50MM					
Weight	Approx. 400g after packing (250g for ET4420).					
Enclosure material	Self extinguishing plastics.					
While cleaning the device	ce, solvents (thinner, gasoline, acid etc.) or corrosive materials must not be used.					













Please see page 7 for Modbus Connection Diagram

ALARM1 AND ALARM2 OUTPUT TYPES





Holding screw 0.4-0.5Nm Equipment is protected throughout by DOUBLE INSULATION.

Logic output of the instrument is not electrically insulated from the internal circuits. Therefore, when using a grounding thermocouple, do not connect the logic output terminals to the ground.

Note :

1) Mains supply cords shall meet the requirements of IEC 60227 or IEC 60245.

2) In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument and it should be easily accessible by the operator.











ENDA ET SERIES PID TEMPERATURE CONTROLLER **MODBUS ADDRESS MAP**

1.1 Memory Map for Holding Registers

	Parameter Number	Holding Register Addresses Desimal (Hex)	Data Type	Data Content	Read / Write Permission	Factory Defauls
	Н0	0000d (0000h)	Word	Control output, temperature setpoint value	Read / Write	400
6	H1	0001d (0001h)	Word	Control output, 2nd temperature setpoint value	Read / Write	400
Control Output Parameters	H2	0002d (0002h)	Word	Control output, minimum setpoint value	Read / Write	0
me	H3	0003d (0003h)	Word	Control output, maximum setpoint value	Read / Write	600
ara	H4	0004d (0004h)	Word	Control output, proportional band setpoint value (Adjustable between %0.0 and %100.0)	Read / Write	4
μ	H5	0005d (0005h)	Word	Control output, hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
ltpu	H6	0006d (0006h)	Word	Control output, integral time (Adjustable between 0.1 and 100.0 minute)	Read / Write	40
õ	H7	0007d (0007h)	Word	Control output, derivative time (Adjustable between 0.01 and 1000 minute)	Read / Write	100
tro	H8	0008d (0008h)	Word	Control output, time period setpoint value (Adjustable between 1 and 125 second)	Read / Write	20
Son	H9	0009d (0009h)	Word	Control output, set value power ratio (Adjustable between %0 and %100)	Read / Write	0
0	H10	00000 (00001) 0010d (000Ah)			Read / Write	0
	H11	0011d (000Bh)	Word	Control output, set value power ratio in case of sensor failure (Adjustable between %0 and %100)		0
	H12	, ,		Control output, soft start value	Read / Write	-
	L	0012d (000Ch)		Alarm1 output temperature setpoint value	Read / Write	500
(0)	H13	0013d (000Dh)			Read / Write	0
ers	H14	0014d (000Eh)	Word	· · · · · · · · · · · · · · · · · · ·	Read / Write	600
Parameters	H15	0015d (000Fh)	Word		Read / Write	0
Irar	H16	0016d (0010h)	Word	Alarm1 output hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
	H17	0017d (0011h)	Word	Alarm1 output, integral time (Adjustable between 0.1 and 100.0 minute)	Read / Write	0
put	H18	0018d (0012h)	Word	Alarm1 output, derivative time (Adjustable between 0.01 and 10.00 minute)	Read / Write	0
Output	H19	0019d (0013h)	Word	Alarm1 output, time period setpoint value (Adjustable between 1 and 125 second)	Read / Write	20
	H20	0020d (0014h)	Word	Alarm1 output, set value power ratio (Adjustable between %0 and %100)	Read / Write	0
A1	H21	0021d (0015h)	Word	Alarm1 output, set value power ratio in case of sensor failure (Adjustable between %0 and %100)	Read / Write	0
	H22	0022d (0016h)	Word	Alarm1 output type selection (Values can be given from 0 to 4) (0 = Independent alarm, 1 = Deviation alarm, 2 = Band alarm, 3 = Active alarm after in band time, 4 = Alarm1 output, cooling control selection)	Read / Write	0
ers	H23	H23 0023d (0017h) Word Alarm2 output, temperature setpoint value		Read / Write	500	
put Parameters	H24	0024d (0018h)	Word	Alarm2 output minimum setpoint value limit	Read / Write	0
Para	H25	0025d (0019h)	Word	Alarm2 output maximum setpoint value limit	Read / Write	600
tput	H26	0026d (001Ah)	Word	Alarm2 output, hysteresis value (Adjustable between 1 and 50 °C or °F)	Read / Write	2
A2 Out	H27	0027d (001Bh)	Word	Alarm2 output type selection (Values can be given from 0 to 3) (0 = Independent alarm,	Read / Write	0
<u> </u>	H28	0028d (001Ch)	Word	 1 = Deviation alarm, 2 = Band alarm, 3 = Active alarm after in band time) Input selection number (0 = PT100 Decimal, 1 = Pt100 Non-decimal, 2 = J Decimal, 3 = J Non-decimal, 4 = K Decimal, 5 = K Non-decimal, 6 = L Decimal, 7 = L Non-decimal, 8 = T Decimal, 9 = T Non-decimal, 10 = S Non-decimal, 11 = R Non-decimal. 	Read / Write	5
LS.	H29	0029d (001Dh)	Word	ModBus device address (Adjustable between 1 and 247)	Read / Write	1
Configuration Parameters	H30	0030d (001Eh)	Word	Modbus communication speed (Baudrate) (0 = Modbus cancel, 1 = 2400 bps, 2 = 4800 bps, 3 = 9600 bps, 4 =19200 bps, 5 = 38400 bps)	Read / Write	3
ara	H31	0031d (001Fh)	Word	Digital filter coefficient (Adjustable between 1 and 200, 1 = filter is disable)	Read / Write	10
P	H32	0032d (0020h)	Word	Control output, selection value (0 = C/A2 Control output selection, 1 = SSR Output)	Read / Write	0
tior	H33	0033d (0021h)	Word	Reserved	Read / Write	XX
Irai	H34	0034d (0022h)	Word	Reserved	Read / Write	XX
figu	H35	0035d (0023h)	Word	Offset value	Read / Write	0
Cont	H36	0036d (0024h)	Word	Function control parameter. (23040d (5A00h) self tune stops when this value is entered) (23041d (5A01h) self tune starts when this value is entered) (23042d (5A02h) returns to factory defaults when this value is entered)	Read / Write	0
	H37	0037d (0025h)	Word	Reserved	Read / Write	XX
	H38	0038d (0026h)	Word	Reserved	Read / Write	XX
	H39	0039d (0027h)	Word	Manual control output percentage (Adjustable between %0 and %100)	Read / Write	50





ENDA ET SERIES PID TEMPERATURE CONTROLLER **MODBUS ADDRESS MAP**

1.1 Memory Map for Holding Registers (continue)

	Parameter Number	Holding Register Addresses Desimal (Hex)	Data Type	Data Content	Read / Write Permission	Factory Defauls
	H40	0040d (0028h)	Word	Digital input control parameter (0 = Digital input off, 1 = 2nd set value is selected with digital input, 2 = Manual mode is entered via digital input, 3 = Digital input is passed to display mode	Read / Write	0
	H41	0041d (0029h)	Word	Function key control parameter (0 = Function key off, 1 = 2nd Set value is selected with function key, 2 = Manual mode is entered via function key, 3 = With the function key display mode is entered)	Read / Write	0
ers	H42	0042d (008Ah)	Word	Reserved	Read / Write	XX
ete	H43	0043d (002Bh)	Word	Reserved	Read / Write	ХХ
aram	H44	0044d (002Ch)	Word	Reserved	Read / Write	ХХ
ara	H45	0045d (002Dh)	Word	Reserved	Read / Write	XX
٩	H46	6 0046d (002Eh) Word Reserved		Read / Write	XX	
ration	H47	0047d (002Fh)	Word	Reserved	Read / Write	XX
5	H48	0048d (0030h)	Word	Control output menu, security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
nfig	H49	0049d (0031h)	Word	Alarm1 output menu security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
Co	H50	0050d (0032h)	Word	Alarm2 output menu, security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
	H51	0051d (0033h)	Word	Configuration menu, security parameter (0 = Menu invisible, 1 = Menu programmable, 2 = Menu only visible)	Read / Write	1
	H52	0052d (0034h)	Word	Self tune menu, security parameter (0 = Menu invisible, 1 = Self tune can be done)	Read / Write	1

1.2 Memory Map for Coils

Parameter Number	Coil Addresses	Data Type	Data Content	Read / Write Permission	Factory Defauls
C0	(0000)h	Bit	Alarm2 Status (0 = Active Low ,1 =Active High)	Read / Write	1
C1	(0001)h	Bit	Alarm2 output position in case of Prob failure (0 = Off , 1 = On)	Read / Write	0
C2	(0002)h	Bit	Alarm1 Status (0 = Active Low ,1 =Active High)	Read / Write	1
C3	(0003)h	Bit	Alarm1 output position in case of Prob failure (0 = Off , 1 = On)	Read / Write	0
C4	(0004)h	Bit	Control output configuration (0 = Heat ; 1 = Cool)	Read / Write	0
C5	(0005)h	Bit	Temperature unit (0 = °C ; 1 = °F)	Read / Write	0
C6	(0006)h	Bit	Control outputs active (0 = Control outputs active, 1 = Only display mode)	Read / Write	0
C7	(0007)h	Bit	Controlling according to 2nd temperature setpoint (If C7 = 0 is H0, if C7 = 1 is H1)	Read / Write	0
C8	(0008)h	Bit	Auto/Manual selection (0 = Automatic "Running mode", 1 = Manual "Running mode". In this mode, output generated according to H39 parameter.)	Read / Write	0
C9	(0009)h	Bit	Control format in case of probe failure (0 = H10 proportional control according to percentage value, 1 = Error found before the setpoint control is done with the value of the proportional control	Read / Write	0

1.3 Memory Map for Input Registers

Parameter Number	Input Register Addresses Desimal (Hex)	Data Type	Data Content	Read / Write Permission
10	0000d (0000h)	Word	Measured temperature	Read Only
1	0001d (0001h)	Word	Percentage of analog output	Read Only
12	0002d (0002h)	Word	Measurement error codes 0 = No error, 1 = Sensor disconnected or broken, 2 = Lower scale error, 3 = Upper scale error, 4 = PT100 short circuit or temperature too low, 5 = Wrong input selection	Read Only
13	0003d (0003h)	Word	Self tune condition codes 0 = No error, 1 = Initial temperature is higher than 60% setpoint value, 2 = Calculating PID parameters, 3 = Calculating power set parameters	Read Only
14	0004d (0004h)	Word	Current (active) temperature setpoint.	Read Only
15	0005d (0005h)	Word	Reserved	Read Only
6	0006d (0006h)	Word	Current (active) decimal point value (0 = No decimal point, 1 = 0.0 Decimal point is tenths	Read Only

1.4 Memory Map for Software Revision Input Registers

Software Revision 61472d (F020h) 14 Word	Software name and update is read in ASCII format and as 14 word.	Read Only		
	Sample : ET4420-01 03 Dec 2013. Memory Formats :			
	Word Word Word Word Word Word Word Word			
	T E 4 4 0 2 0 - 1 1 3 0 D C E 2 1 0 3			
	NOTE : To view each word correctly by changing the byte sequences should be displayed as ASCII TEXT			





ENDA ET SERIES PID TEMPERATURE CONTROLLER MODBUS ADDRESS MAP

1.5 Memory Map for Discrete input

Parametre Numarasi	Discrete Input Addresses	Data Type		Read / Write Permission
D0	(0000)h	Bit	C/A2 Control output status (0 = OFF ,1 = ON)	Read Only
D1	(0001)h	Bit	A1 Output status (0 = OFF , 1 = ON)	Read Only
D2	(0002)h	Bit	SSR Output status (0 = OFF ,1 = ON)	Read Only
D3	(0003)h	Bit	Digital input status (0 = OFF ,1 = ON)	Read Only

2. MODBUS ERROR MESSAGES

Modbus protocol has two types error, communication error and operating error. Reason of the communication error is data corruption in transmission. Parity and CRC control should be done to prevent communication error. Receiver side checks parity and CRC of the data. If they are wrong, the message will be ignored. If format of the data is true but function doesn't perform for any reason, operating error occurs. Slave realizes error and sends error message. Most significant bit of function is changed '1' to indicate error in error message by slave. Error code is sent in data section. Master realizes error type via this message.

ModBus Error Codes

Error Code	Name	Meaning	
01 ILLEGAL FUNCTION		The function code received in the query is not an allowable action for the slave. If a Poll Program Complete command was issued, this code indicates that no program function preceded it.	
02	ILLEGAL DATA ADDRESS	The data address received in the query is not an allowable address for the slave.	
03 ILLEGAL DATA VALUE		A value contained in the query data field is not an allowable value for the slave.	

Message example;

Structure of command message (Byte Format)

Device Addres	(0A)h				
Function Code	Function Code				
Beginning address	MSB	(04)h			
of coils.	LSB	(A1)h			
Number of coils (N)	MSB	(00)h			
	LSB	(01)h			
CRC DATA	LSB	(AC)h			
CRC DATA	MSB	(63)h			

Structure of response message (Byte Format)

Device Addres	(0A)h
Function Code	(81)h
Error Code	(02)h
	(B0)h
CRC DATA	(53)h

As you see in command message, coil information of (4A1)h = 1185 is required but there isn't any coil with 1185 address. Therefore error code with number (02) (Illegal Data Address) sends.





